

// **250420_Solax_SwitchFanAndRCSockets**

// This program uses the data from the solar panel inverter to switch RC sockets
// of power users "on" or "off" in such a way that the power of the solar panels
// is used directly during the time it is produced.
// The power users are plugged in remote controllerd sockets which are
// controole by a small 433MHz transmitter.
// To provide extra external cooling, a fan is switched on at a certain temperature
// a green LED will indicate the use of the inverter's data.
// a blue LED will indicate that enough power is delivered for RCA (boiler socket)

// **Hardware connections:**

// Arduino MAX 485
// D4 DE Data Enable (DEPin)
// D3 RE Receive Enable(REPin)
// D2 RO Receive Out (SSerialRX)
// D5 DI Data In (SSerialTX)
// 3.3V VCC (5V also allowed)
// GND GND
// RS485 A SOLAX Inverter RJ45 pin 4
// RS485 B SOLAX inverter RJ45 pin 5
// D7 Green LED to indicate datareception from inverter > 50 W
// D8 To FET switching the fan
// D9 To Blue LED: Boiler socket "on"
// 5V VCC of 433MHZ TX, LED of Boiler circuit, MODE switch centre pin
// GND GDD of FanFET, Emitter, Pulldown resistors and GND 433MHZ TX
// D10 Mode-switch down Input 5V
// D11 Mode-switch up Input 5V
// D12 Data to 433MHz TX

// **Mode switch:**

// A 3-way switch let you choose from different CONDITIONS
// 3-WAY SWITCH UP: BOILER socket RCA "on" independent on power_Solax
// RCB socket is switched "on", when there's excess power
// 3-WAY SWITCH DOWN: BOILER socket RCA "off"
// RCB and RCC are switched depending on the delivered power
// 3-WAY SWITCH MIDDLE position: BOILER RCA "power regulated"
// RCB socket is switched "on", when there's excess power

```
#include <SoftwareSerial.h>
#define SSerialRX 2 // Receive Out
#define REPin 3 // Receive Enable
#define DEPin 4 // Data Enable
#define SSerialTX 5 // Data In
#define RS485Receive LOW
#define RS485Transmit HIGH
#define SolaxDataLED 7 // indicator Solax provides data
#define FanRelayPin 8
#define BoilerOnPin 9
#define ModeAlwaysOffPin 10 // Input, set menu choice 3 when HIGH
#define ModeAlwaysOnPin 11 // Input, set menu choice 1 when HIGH
#define RCDataPin 12 // Data to the 433 MHz transmitter
```

```

SoftwareSerial RS485Serial(SSerialRX, SSerialTX);
byte AddressInput[] = {0xAA,0x55,0x00,0x00, 0x00,0x00, 0x10, 0x01, 0x0F,
//      Header, AccesPoint, Solax X1 ,Contr, Func, Length
    0x31,0x32,0x33,0x34,0x35,0x36,0x37,0x37,0x36,0x35,0x34,0x33,0x32,0x31, 0x0A,0x04,0x01};
//  Serialnumber data 0 ----->13 ,address, checksum
byte RequestData[]={0xAA,0x55, 0x00,0x00, 0x00,0x0A , 0x11, 0x02, 0x00, 0x01,0x1C};
//      Header , Source , SOLAX ,Control,Func,Length, Check 2b
byte DataInput[63];

```

// Declaration and on-off settings (power in watts)

```

int power_RCA_Off = 1550; // 1475 winter boiler socket
int power_RCA_On = 1600; // 1525 winter
int power_RCBPlus_Off = 2000; // when used in mode 2
int power_RCBPlus_On = 2050; // when RCA is on
int power_RCB_Off = 550; // when used in mode 3
int power_RCB_On = 600; // when RCA is off
int power_RCC_Off = 1050; // mode 3 only
int power_RCC_On = 1100;
int temp_Fan_On = 31; // °C
int temp_Fan_Off = 27;
int temp_Solax = 30; // start with the fan running
int switchOffDelay = 2000; // millisecs delay before switching off
int loopdelay = 9000; // 9 seconds

```

// Declarations and conditions

```

int MenuChoice = 2; // switch condition
int power_Solax = 0; // data from inverter
float voltage_Grid = 0.0; // data from inverter
byte InByte = 0;
bool socketA_allowedOn = false; // set by powervalue or switch
bool socketB_allowedOn = false;
bool socketC_allowedOn = false;
bool socketA_switchedOn = false; // runtime situation
bool socketB_switchedOn = false;
bool socketC_switchedOn = false;

```

// Setting of the used RC switches

```

// delay times (pinData HIGH or LOW situations) in µ seconds:
#define Bit24HighUp 998 //44 samplepoints
#define Bit24HighDown 476 //21 samplepoints
#define Bit24LowUp 295 //13 samplepoints
#define Bit24LowDown 1179 //52 samplepoints

#define Bit32HighUp 1429 //66 samplepoints
#define Bit32HighDown 590 //26 samplepoints
#define Bit32LowUp 408 //18 samplepoints
#define Bit32LowDown 1610 //71 samplepoints

```

```

#define StartDelay24LowUp 400
#define StartDelay24LowDown 2250
#define StartDelay32LowUp 408
#define StartDelay32LowDown 7188

// commands for the 3 sockets; 24 bit pattern is send 6x, 32 bit pattern 4x
bool S24[6][24] = {{0,0,1,1,0,0,0,0,1,0,1,1,1,0,1,0,0,0,1,1,0,1,0,1}, // A_ON
    {0,0,1,1,0,1,1,1,0,0,0,0,1,1,0,1,0,1,0,0,0,1,0,1}, // A_OFF
    {0,0,1,1,1,0,1,1,1,1,0,0,0,0,1,1,0,1,1,0,1,1,0,0}, // B_ON
    {0,0,1,1,1,1,0,0,1,1,1,0,1,1,0,0,1,1,1,1,1,0,0}, // B_OFF
    {0,0,1,1,0,1,1,0,1,1,1,0,0,0,0,1,1,0,1,1,1,1,0}, // C_ON
    {0,0,1,1,0,1,0,1,0,1,1,0,1,0,0,0,0,0,1,1,1,1,0}}; // C_OFF
bool S32[6][32] =
    {{0,0,1,1,1,0,1,0,1,1,1,1,0,1,1,1,1,1,1,0,0,1,1,0,1,0,1,0,1}, // A_ON
    {1,0,1,1,1,1,0,0,1,1,1,0,1,1,1,0,0,1,1,0,1,1,1,1,0,0,1,0,1,0,1}, // A_OFF
    {1,1,1,1,0,0,0,1,0,1,0,1,1,1,1,1,1,1,1,0,1,0,1,1,0,1,0,0,1,1}, // B_ON
    {1,0,0,0,1,0,1,1,1,0,0,0,1,1,1,0,1,0,0,1,1,0,0,0,1,0,0,1,0,0,1,1}, // B_OFF
    {1,1,1,1,1,1,1,1,1,0,1,1,0,0,1,1,0,1,0,1,0,0,1,1,1,0,1,1,0,1,1}, // C_ON
    {1,1,0,1,0,0,1,1,0,0,1,0,0,0,0,1,1,0,0,0,0,0,0,1,1,0,0,1,1,0,1,1}}; // C_OFF

// Function to set the menu value according to the 3-way switch
void SetMenu()
{
    if(digitalRead(ModeAlwaysOnPin) == HIGH)
        MenuChoice = 1; //Boilersocket always on (UP)
    if(digitalRead(ModeAlwaysOffPin) == HIGH)
        MenuChoice = 3; //Boilersocket always off (DOWN)
    if((digitalRead(ModeAlwaysOnPin) == LOW) && (digitalRead(ModeAlwaysOffPin) == LOW))
        MenuChoice = 2; // Boilersocket power_Solax regulated
    Serial.println();
    Serial.print("ModeSwitch Socket On ");
    Serial.print(digitalRead(ModeAlwaysOnPin));
    Serial.println();
    Serial.print("ModeSwitch Socket Off ");
    Serial.print(digitalRead(ModeAlwaysOffPin));
    Serial.println();
}

// Function to assign an address to the Solax inverter
void AssignAddress()
{
    digitalWrite(REPin, RS485Transmit);
    digitalWrite(DEPin, RS485Transmit);
    RS485Serial.write(AddressInput, sizeof(AddressInput));
    delay(100);
    digitalWrite(REPin, RS485Receive);
    digitalWrite(DEPin, RS485Receive);
    delay(1000);
}

```

void GetSolaxData()

```
{
  digitalWrite(REPin, RS485Transmit); // set send mode
  digitalWrite(DEPin, RS485Transmit);
  RS485Serial.write(RequestData,sizeof(RequestData));
  digitalWrite(REPin, RS485Receive); // set receive mode
  digitalWrite(DEPin, RS485Receive);
  int index = 0;
  while(RS485Serial.available())
  {
    InByte = (byte)RS485Serial.read();
    DataInput[index] = InByte;
    index++;
  } // update the data values of interest
  power_Solax = DataInput[28] + 256 * DataInput[27];
  if (power_Solax > 0)
  {
    temp_Solax = DataInput[10];
    voltage_Grid = (DataInput[24] + 256 * DataInput[23]) / 10.0;
    Serial.println();
    Serial.print("Watts: ");
    Serial.print(power_Solax);
    Serial.println();
    Serial.print("Temperature: ");
    Serial.print(temp_Solax);
    Serial.println();
    Serial.print("gridVoltage: ");
    Serial.print(voltage_Grid);
    Serial.println();
  }
}
```

void switchRCsockets(int mode)

```
{
  if (mode == 1) // RCA(Boiler)always on
  {
    if(socketA_switchedOn == false)
    {
      switchRC(0); // Socket A ON
      socketA_switchedOn = true;
      digitalWrite(BoilerOnPin, HIGH);
    }
    if(power_Solax >= power_RCBPlus_On)
    {
      socketB_allowedOn = true;
      if(socketB_switchedOn == false)
      {
        switchRC(2); // Socket B ON
      }
    }
  }
}
```

```

    socketB_switchedOn = true;
}
}
if((power_Solax < power_RCBPlus_Off) && (socketB_switchedOn == true))
{
    delay(switchOffDelay); // delay and measure again
    GetSolaxData();
    if(power_Solax < power_RCBPlus_Off)
    {
        socketB_allowedOn = false;
        switchRC(3); // Socket B OFF
        socketB_switchedOn = false;
    }
}
}
if (mode == 2) // all sockets power_Solax regulated
{
    if(power_Solax >= power_RCA_On)
    {
        socketA_allowedOn = true;
        if(socketA_switchedOn == false)
        {
            switchRC(0); // Socket A ON
            socketA_switchedOn = true;
            digitalWrite(BoilerOnPin, HIGH);
        }
    }
    if((power_Solax < power_RCA_Off) && (socketA_switchedOn == true))
    {
        delay(switchOffDelay); // delay and measure again
        GetSolaxData();
        if(power_Solax < power_RCA_Off)
        {
            socketA_allowedOn = false;
            switchRC(1); // Socket A OFF
            socketA_switchedOn = false;
            digitalWrite(BoilerOnPin, LOW);
        }
    }
    if(power_Solax >= power_RCBPlus_On)
    {
        socketB_allowedOn = true;
        if(socketB_switchedOn == false)
        {
            switchRC(2); // Socket B ON
            socketB_switchedOn = true;
        }
    }
    if((power_Solax < power_RCBPlus_Off) && (socketB_switchedOn == true))

```

```

{
  delay(switchOffDelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCBPlus_Off)
  {
    socketB_allowedOn = false;
    switchRC(3); // Socket B OFF
    socketB_switchedOn = false;
  }
}
}
if(mode == 3) // RCA (boiler) off switch B and C earlier
{
  if(socketA_switchedOn == true)
  {
    switchRC(1); //Socket A OFF
    socketA_switchedOn == false;
    digitalWrite(BoilerOnPin, LOW);
  }
  if(power_Solax >= power_RCB_On)
  {
    socketB_allowedOn = true;
    if(socketB_switchedOn == false)
    {
      switchRC(2); // Socket B ON
      socketB_switchedOn = true;
    }
  }
}
if((power_Solax < power_RCB_Off) && (socketB_switchedOn == true))
{
  delay(switchOffDelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCB_Off)
  {
    socketB_allowedOn = false;
    switchRC(3); // Socket B OFF
    socketB_switchedOn = false;
  }
}
if(power_Solax >= power_RCC_On)
{
  socketC_allowedOn = true;
  if(socketC_switchedOn == false)
  {
    switchRC(4); // Socket C ON
    socketC_switchedOn = true;
  }
}
if((power_Solax < power_RCC_Off) && (socketC_switchedOn == true))

```

```

{
  delay(switchOffDelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCC_Off)
  {
    socketC_allowedOn = false;
    switchRC(5); // Socket C OFF
    socketC_switchedOn = false;
  }
}
}
Serial.println();
Serial.print(" socketA_switchedOn = ");
Serial.print(socketA_switchedOn);
Serial.println();
Serial.print(" socketB_switchedOn = ");
Serial.print(socketB_switchedOn);
Serial.println();
Serial.print(" socketC_switchedOn = ");
Serial.print(socketC_switchedOn);
Serial.println();
}

```

// Function to send the TX signal dependend on socket and command

void switchRC(int commandNumber)

```

{
  int bitNumber;
  int bitPattern;
  Serial.println();
  Serial.print("Function switchRC called. Commandnumber: ");
  Serial.print(commandNumber);
  for (bitPattern = 0; bitPattern < 6; bitPattern++) // 24 bit part 6 times
  {
    // start with extra LOW part
    digitalWrite(RCDataPin, HIGH);
    delayMicroseconds(StartDelay24LowUp);
    digitalWrite (RCDataPin, LOW);
    delayMicroseconds(StartDelay24LowDown);
    for (bitNumber = 0; bitNumber < 24; bitNumber++)
    {
      if (S24[commandNumber][bitNumber] == HIGH)
      {
        digitalWrite (RCDataPin, HIGH);
        delayMicroseconds(Bit24HighUp);
        digitalWrite (RCDataPin, LOW);
        delayMicroseconds(Bit24HighDown);
      }
      else
      {

```

```

        digitalWrite (RCDataPin, HIGH);
        delayMicroseconds(Bit24LowUp);
        digitalWrite (RCDataPin, LOW);
        delayMicroseconds(Bit24LowDown);
    }
}
}
for (bitPattern = 0; bitPattern < 4; bitPattern++) // 32bits part 4 times
{
    //start with an extra long LOW
    digitalWrite (RCDataPin, HIGH);
    delayMicroseconds(StartDelay32LowUp);
    digitalWrite (RCDataPin, LOW);
    delayMicroseconds(StartDelay32LowDown);
    for (bitNumber = 0; bitNumber < 32; bitNumber++)
    {
        if (S32[commandNumber][bitNumber] == HIGH)
        {
            digitalWrite (RCDataPin, HIGH);
            delayMicroseconds(Bit32HighUp);
            digitalWrite (RCDataPin, LOW);
            delayMicroseconds(Bit32HighDown);
        }
        else
        {
            digitalWrite (RCDataPin, HIGH);
            delayMicroseconds(Bit32LowUp);
            digitalWrite (RCDataPin, LOW);
            delayMicroseconds(Bit32LowDown);
        }
    }
}
}
}

void setup()
{
    pinMode(REPin, OUTPUT);
    pinMode(DEPin, OUTPUT);
    pinMode(SSerialRX, INPUT);
    pinMode(SSerialTX, OUTPUT);
    pinMode(FanRelayPin, OUTPUT);
    pinMode(ModeAlwaysOnPin, INPUT);
    pinMode(ModeAlwaysOffPin, INPUT);
    pinMode(RCDataPin, OUTPUT);
    pinMode(SolaxDataLED, OUTPUT);
    pinMode(BoilerOnPin, OUTPUT);
    Serial.begin(9600);
    Serial.println("_250420_Solax_SwitchFanAndRCSockets");
    Serial.println();
    digitalWrite(REPin, RS485Receive);

```



```

digitalWrite(DEPin, RS485Receive);
digitalWrite(FanRelayPin, LOW); // Fan off
digitalWrite(SolaxDataLED, LOW);
digitalWrite(BoilerOnPin, LOW);
switchRC(1); // switch off sockets just in case they are on
switchRC(3);
switchRC(5);
RS485Serial.begin(9600); // set data rate
Serial.println();
Serial.println(" Assigning address to Inverter....");
AssignAddress();
delay(1000);
GetSolaxData();
delay(200);
}

```

void loop()

```

{
  GetSolaxData();
  delay(200);
  if(power_Solax == 0) // re-assign address when needed
  {
    delay(30000);
    GetSolaxData();
    if(power_Solax == 0)
    {
      Serial.println();
      Serial.println("Assigning address again....");
      AssignAddress();
      delay(1000);
    }
  }
  SetMenu();      // Check the menu switch
  delay(200);
  if(power_Solax > 50) // Indicate data input with green LED
    digitalWrite(SolaxDataLED, HIGH);
  if(power_Solax < 10)
    digitalWrite(SolaxDataLED, LOW);
  if (temp_Solax >= temp_Fan_On)
    digitalWrite(FanRelayPin, HIGH); // Fan on
  if ((temp_Solax < temp_Fan_Off) && (power_Solax > 0))
    digitalWrite(FanRelayPin, LOW); // Fan off
  switchRCsockets(MenuChoice);
  delay(loopdelay);
}
// Sketch uses 7836 bytes (24%) of program storage space.
// Global variables use 1059 bytes (51%) of dynamic memory.

```